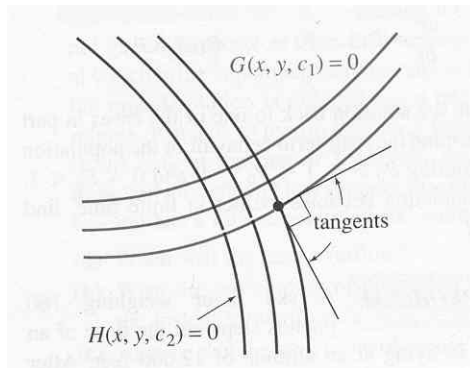


Differential Equations

Project One

1. Choose *one* of the following two questions:

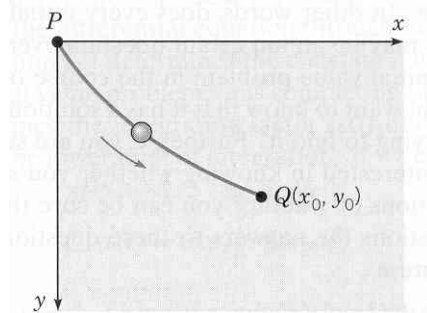
A. **Orthogonal Trajectories**¹ When all curves in a family $G(x, y, c_1) = 0$ intersect orthogonally all curves in another family $H(x, y, c_2) = 0$, the families are said to be *orthogonal trajectories* of each other.



- Do some reading about orthogonal trajectories and their applications in the sciences, then write a short (1 – 2 page) report on your findings. Be sure you understand what you write – please do not transcribe the contents of a website for me. Also, please include a list of sources that you use.
- Illustrate your report by finding the orthogonal trajectories for the family $y = 1/(x + c_1)$. Use a graphing utility to graph both families on the same axes.
- Find the orthogonal trajectories for the family $x^2 - xy + y^2 = c_1$ (Hint: to solve the resulting D.E., see problem #30 from section 2.2, or the notes from class).

¹ Taken from *Differential Equations with Computer Lab Experiments* by Dennis G. Zill

- B. **The Brachistochrone Problem**² One of the famous problems in the history of mathematics is the *brachistochrone problem*: to find a curve along which a particle will slide without friction in the minimum time from one given point P to another Q , the second point being lower than the first, but not directly beneath it.



- (a) Do some reading about the brachistochrone problem and its historical significance. Why is this problem important still? Report your findings in a short (1 – 2 page) paper. Be sure you understand what you write – please do not transcribe the contents of a website for me. Also, please include a list of sources that you use.
- (b) If we take the point P to be the origin, and let the lower point Q have coordinates (x_0, y_0) , the curve of minimum time is given by a function $y(x)$ that satisfies the differential equation $\left(1 + \left(\frac{dy}{dx}\right)^2\right)y = k^2$, where k is a positive constant. Solve this differential equation for $\frac{dy}{dx}$. Why is it necessary to choose the positive square root?
- (c) Introduce the new variable t by the relation $y = k^2 \sin^2 t$, and show that the equation found in part (b) then takes the form $2k^2 \sin^2 t \, dt = dx$.
- (d) By letting $\theta = 2t$, show that the solution of the equation from part (c) for which $x = 0$ when $y = 0$ is given by
- $$x = k^2(\theta - \sin \theta)/2, \quad y = k^2(1 - \cos \theta)/2.$$
- These are the parametric equations of the solution to the original differential equation that passes through $(0,0)$. The graph of these equations is the *cycloid*.
- (e) Finally, if we choose the constant k carefully, then the cycloid also passes through the point (x_0, y_0) and is the solution of the brachistochrone problem. Find k if $x_0 = 1$ and $y_0 = 2$.

² Adapted from problem #32 in Section 2.3 of our book.

2. **Population Modeling**³ If a constant number of animals h have been removed or harvested per unit time, then the population $P(t)$ of animals is modeled by the initial-value problem $\frac{dP}{dt} = P(a - bP) - h$, $P(0) = P_0$, where a , b , h and P_0 are positive constants.

(a) Without solving, analyze the effect of h on the population by finding the critical points of the equation and phase portraits in the cases $0 < h < \frac{a^2}{4b}$, $h = \frac{a^2}{4b}$, and $h > \frac{a^2}{4b}$. Where do these cases come from? Use the phase portraits to sketch the behavior of solution curves for various values of P_0 . Use the phase portraits and solution curves to determine the long term behavior of the population. Does the population ever become extinct?

(b) Find an explicit solution of $\frac{dP}{dt} = P(5 - P) - 4$, $P(0) = P_0$ and relate the solution to one of the cases in part (a). Determine the long-term behavior of the population by considering $P_0 > 4$, $1 < P_0 < 4$, and $0 < P_0 < 1$. If the population becomes extinct in finite time, find that time.

³ This problem is adapted from *Differential Equations with Computer Lab Experiments* by Dennis G. Zill