

# Notes 3. Math 313 Linear algebra

(p.1)

## 2.5. The Matrix Inverse.

Definition Given a square matrix  $A^{n \times n}$  we say  $A$  is invertible if there is a square matrix  $A^{-1}$  such that  $AA^{-1} = A^{-1}A = I^{n \times n}$ .

Example. Let  $A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ . Call an unknown matrix  $X = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$  to stand in for  $A^{-1}$  if  $A^{-1}$  exists. Then  $AX = I$  means

$$A \begin{bmatrix} x & y \\ y & z \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}. \text{ So in particular } A \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

and  $A \begin{bmatrix} y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . So we must solve two systems simultaneously with the same matrix  $A$  of coefficients.

We do this by reducing the doubly augmented matrix.

$$\left[ \begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{array} \right] \xrightarrow{R_2 = R_2 - R_1} \left[ \begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 0 & 1 & -1 & 1 \end{array} \right]$$

To read off the solution in an easy way we continue to reduce the whole augmented matrix:

$$\xrightarrow{R_1 = R_1 - R_2} \left[ \begin{array}{cc|cc} 1 & 0 & 2 & -1 \\ 0 & 1 & -1 & 1 \end{array} \right]$$

Therefore we have  $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$  and  $\begin{bmatrix} y \\ z \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$  and  $X = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$

Hence we have found  $X$  so that  $AX = I$ . We also check easily that  $XA = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$ . So  $X = A^{-1}$ .

(p.2)

Let's review the method by which we produced  $A^{-1}$  above by introducing elimination matrices.

For  $E_{21} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$  we have  $E_{21}A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ , and then following by  $E_{12} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$  we arrive at  $E_{12}E_{21}A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ .

Therefore  $M = E_{12}E_{21}$  is a left inverse of  $A$ .

But we already found a right inverse  $X$  so that  $AX = I$ . These left and right inverses must be the same as follows:

$$M = MI = M(AX) = (MA)X = IX = X.$$

We have the result that:  $A^{n \times n}$  is invertible if and only if  $A$  has  $n$  pivots in the row reduction, or because  $A$  is square, if and only if  $A$  may be reduced after appropriate row multiplications to the identity matrix. Therefore schematically we have

$$[A \mid I] \xrightarrow{\text{"row reduction"}} [I \mid A^{-1}] \text{ whenever } A \text{ is invertible.}$$

Example. A non-invertible case.

$$\text{Let } A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & -2 & 1 \\ 2 & 0 & 4 \end{bmatrix}$$

Show  $A^{-1}$  does not exist.

$$[A \mid I] = \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 & 1 & 0 \\ 2 & 0 & 4 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 = R_2 - R_1} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -4 & -2 & -1 & 1 & 0 \\ 2 & 0 & 4 & 0 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{R_3 = R_3 - 2R_1} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -4 & -2 & -1 & 1 & 0 \\ 0 & -4 & -2 & -2 & 0 & 1 \end{array} \right] \xrightarrow{R_3 = R_3 - R_2} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -4 & -2 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & -1 & 1 \end{array} \right]$$

Since  $A$  does not have 3 pivots,  $A$  is not invertible. No 3rd pivot.

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## Inverse of a product of invertible matrices

Suppose that  $A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$  with  $A^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$   
and  $B = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix}$  with  $B^{-1} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix}$ .

What is  $(AB)^{-1}$ ?

Claim  $(AB)^{-1} = B^{-1}A^{-1}$ . Indeed,  $(B^{-1}A^{-1})(AB)$

$$= B^{-1}(A^{-1}A)B = B^{-1}IB = B^{-1}B = I. \text{ So}$$

$B^{-1}A^{-1}$  is a left inverse of  $AB$ , so is an inverse of  $AB$ .

$$\text{Therefore } (AB)^{-1} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 11 & -8 \\ -4 & 3 \end{bmatrix}$$

To check this, note that  $AB = \begin{bmatrix} 3 & 8 \\ 4 & 11 \end{bmatrix}$  and  $\begin{bmatrix} 11 & -8 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 3 & 8 \\ 4 & 11 \end{bmatrix} = \begin{bmatrix} 10 & 0 \\ 0 & 1 \end{bmatrix}$

Exercise. 2.5 #26. Let  $A = \begin{bmatrix} 1 & 2 \\ 2 & 6 \end{bmatrix}$ . Find elimination

matrices  $E_{21}$  and  $E_{12}$  and a diagonal matrix  $D^{-1}$  that reduces  $A$  to the identity.

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 6 \end{bmatrix} \xrightarrow{R_2 = R_2 - 2R_1} \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix} \xrightarrow{R_1 = R_1 - R_2} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

So  $E_{21} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$ ,  $E_{12} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$  and  $D^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$ .

$$\text{Therefore } A^{-1} = D^{-1}E_{12}E_{21} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \\ = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 3 & -1 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 3 & -1 \\ -1 & \frac{1}{2} \end{bmatrix}$$

Inverse of a 2x2 matrix

We first show the inverse of a special 2x2 matrix

$$S = \begin{bmatrix} a & b \\ 0 & d \end{bmatrix}, \text{ We have } \left[ \begin{array}{cc|cc} a & b & 1 & 0 \\ 0 & d & 0 & 1 \end{array} \right] \rightarrow \left[ \begin{array}{cc|cc} 1 & \frac{b}{d} & \frac{1}{a} & 0 \\ 0 & 1 & 0 & \frac{1}{d} \end{array} \right]$$

by dividing both rows by the corresponding pivot values. Here we assume both  $a$  and  $d$  are not zero else there is no inverse (because there wouldn't be a 2<sup>nd</sup> pivot).

$$\text{Finally } \left[ \begin{array}{cc|cc} 1 & \frac{b}{d} & \frac{1}{a} & 0 \\ 0 & 1 & 0 & \frac{1}{d} \end{array} \right] \xrightarrow{R_1 = R_1 - \frac{b}{d} R_2} \left[ \begin{array}{cc|cc} 1 & 0 & \frac{1}{a} & -\frac{b}{ad} \\ 0 & 1 & 0 & \frac{1}{d} \end{array} \right]$$

Notice that the inverse may be written as

$$S^{-1} = \frac{1}{ad} \begin{bmatrix} d & -b \\ 0 & a \end{bmatrix} \text{ in this special case.}$$

For the general 2x2 we must first find the two pivots  $a$  &  $d$ :

$$\left[ \begin{array}{cc|cc} a & b & 1 & 0 \\ c & d & 0 & 1 \end{array} \right] \xrightarrow{R_2 = R_2 - \frac{c}{a} R_1} \left[ \begin{array}{cc|cc} a & b & 1 & 0 \\ 0 & d - \frac{cb}{a} & -\frac{c}{a} & 1 \end{array} \right]$$

Now we already know the inverse of  $S_1 := \begin{bmatrix} a & b \\ 0 & d - \frac{cb}{a} \end{bmatrix}$ , with

$$\text{namely } S_1^{-1} = \frac{1}{a(d - \frac{bc}{a})} \begin{bmatrix} d - \frac{bc}{a} & -b \\ 0 & a \end{bmatrix} \text{ by the special case.}$$

$$\text{with } d_1 = \frac{ad - bc}{a}$$

Therefore multiplying  $S_1^{-1} * \begin{bmatrix} 1 & 0 \\ -\frac{c}{a} & 1 \end{bmatrix}$ , we obtain  $A^{-1}$

$$\text{as follows: } \frac{1}{ad - bc} \begin{bmatrix} \frac{ad - bc}{a} & -b \\ 0 & a \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\frac{c}{a} & 1 \end{bmatrix} = \frac{1}{ad - bc} \begin{bmatrix} ad & -b \\ -c & a \end{bmatrix}$$

$$\text{or } A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \text{ exists if and only if } ad - bc \neq 0.$$